

Shell Exploration & Production

Algebraic Computations on Noisy, Measured Data

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File Title

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Contents

- **Industrial Application of Computer Algebra**
- **ApVI Calculated**

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The 'Champions Field', South-Chinese Sea, offshore Brunei



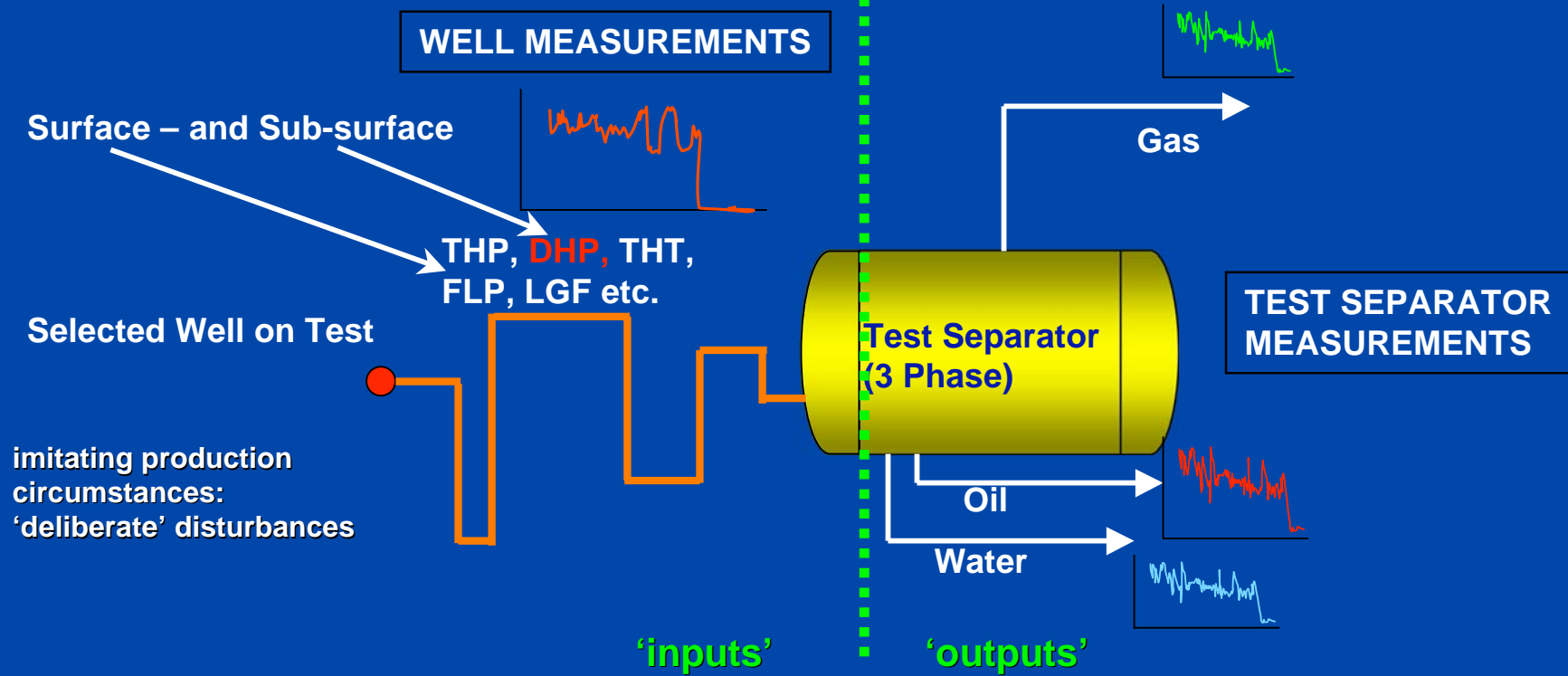
transportation tubing

well heads

headers (test- and bulk) separators



Production Relation for an Oil Well



output = function of inputs

output = **polynomial function**

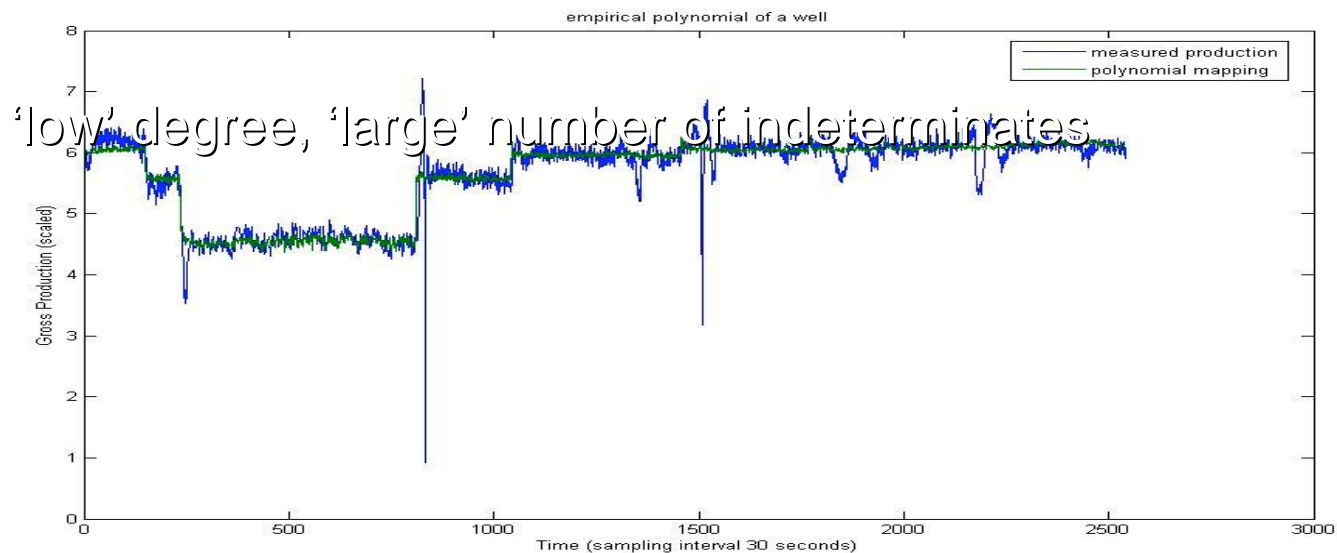
variables of polynomial function

{ input
physical relation between inputs

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example of a polynomial well production

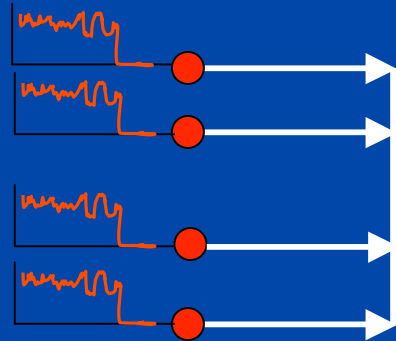
$$\begin{aligned} \text{production} = & 2.9232 * (\sqrt{((DHP_1 - DHP_{tu}) * DHP_{tu}) * FLP}) - \\ & 2.7075 * (\sqrt{((DHP_1 - DHP_{tu}) * DHP_{tu}) * DHP_1}) + \\ & 2.9517 * \sqrt{((DHP_{tu} - THP) * THP)} - \\ & 1.2158 * (\sqrt{((DHP_{tu} - THP) * THP) * THP}) + \\ & 0.3856 * (\sqrt{((THP - FLP) * FLP) * DHP_{tu}}) + \\ & 2.5594 * (\sqrt{((DHP_1 - DHP_{tu}) * DHP_{tu}) * DHP_{tu}}) \end{aligned}$$



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Motivating Example

production well A
production well B
production well C
production well D



transportation
Line



Gas

total
production

Oil

Water

measured

construct polynomial

constructed polynomials

Total Production ∈ Ideal Generated by Separate Productions

$$prod_{total} = g_A prod_{well A} + \dots + g_D prod_{well D}$$

polynomials: interactions between productions

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construction of well production polynomial

$$P = \mathbb{R}[x_1, \dots, x_n]$$

indeterminates

$$x_1 = THP, x_2 = \sqrt{((DPT - P_{tubing})P_{tubing}), \dots}$$

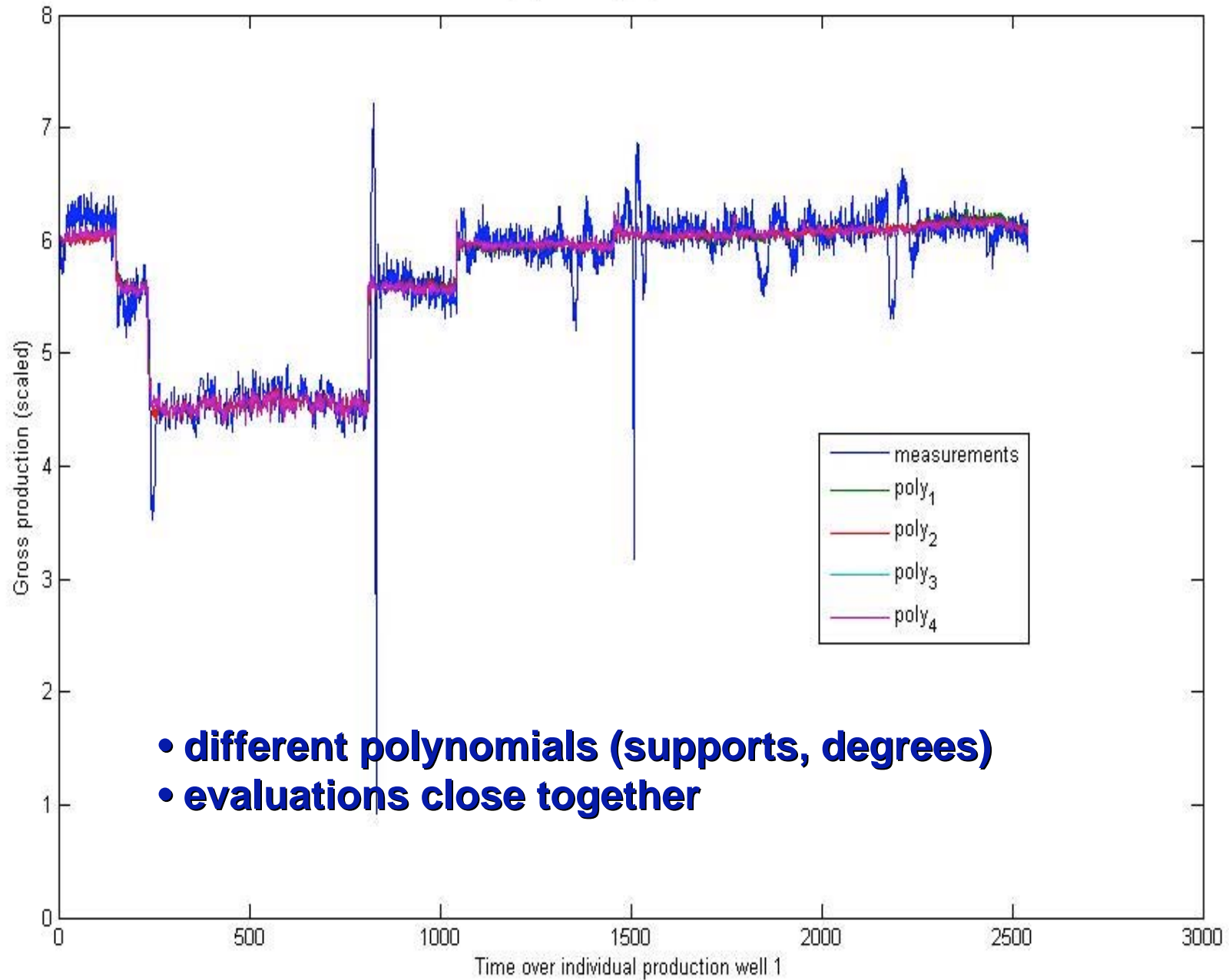
production polynomial f has to be fitted to a set of points:

$$\mathbb{X} = \{p_1, \dots, p_s\} \subset \mathbb{R}^n$$

evaluations of indeterminates at first data point

number of points in the order of thousands not uncommon

different polynomials f_1 , 'equivalent' evaluations



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relations in the data, among the indeterminates

$$\begin{aligned} f &\in P \text{ polynomial estimated from noisy data} \\ \psi_{p_i} &: P \rightarrow \mathbb{R} \text{ evaluation homomorphism : } h \mapsto h(p_i) \\ \delta &\in \mathbb{R}^+ \\ E_f &= \{g \in P \mid |g(p) - f(p)| \leq \delta \forall p \in \mathbb{X}\} \end{aligned}$$

~~*constructed polynomials 'per set' E_f ??*~~

transitivity fails

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Small Polynomials:

$$r \in P \text{ small polynomial} \Leftrightarrow |\psi_p(r)| \leq \delta \forall p \in \mathbb{X}$$

Vanishing Ideal

$$I(\mathbb{X}) := \{g \in P \mid \psi_p(g) = 0 \forall p \in \mathbb{X}\}$$

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example

$$p_1 = \dots = p_5 \in \mathbb{R}^2$$
$$f(p_1) = \dots = f(p_5) = 0$$

→ univariate polynomial

perturb points

→ polynomial of degree 5 vanishing on points

- remove the perturbations first before constructing the polynomials
- construct polynomial allowing it to pass 'close by' prescribed points

delta-Approximate Vanishing Ideal

$$I_\delta(\mathbb{X}) \quad : \quad \exists G \text{ with normalized coefficient vectors} \\ \text{s.t.} \quad |g(p)| \leq \delta \quad \forall p \in \mathbb{X} \text{ and } g \in G$$

of course we still have:

$$\exists g \in I_\delta(\mathbb{X}), \quad |g(p)| > \delta, \text{ for some } p \in \mathbb{X}$$

Best thing one can do:

Empirical Ring:

$$Q := P / I_{\delta}(X)$$

Empirical Polynomial:

$$f \in Q$$

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HOW TO CALCULATE THE

ApVI

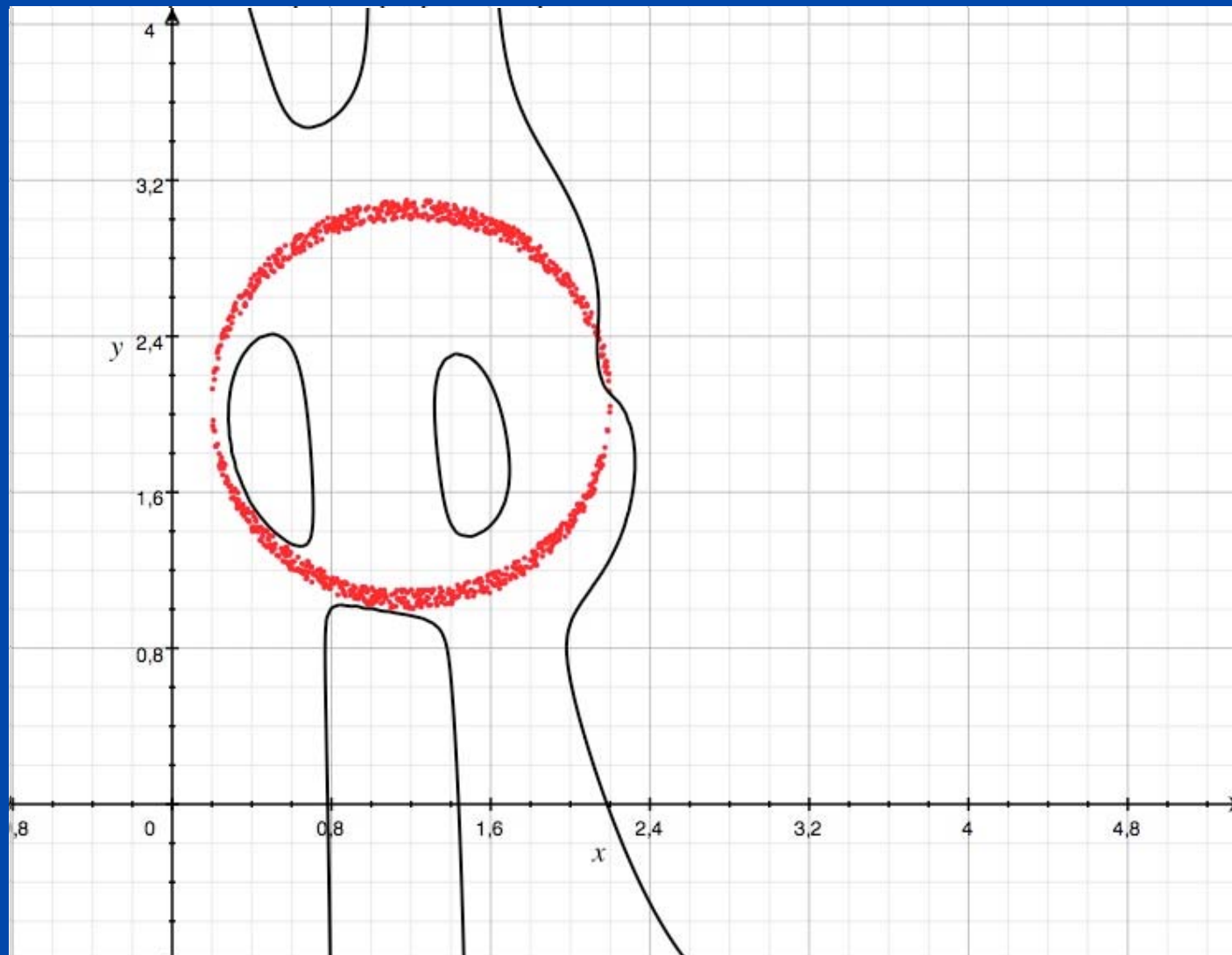
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The Buchberger–Möller algorithm:

1. Set $\mathcal{O} = \emptyset$, $Eval(\mathcal{O}) = \emptyset$ and $G = \emptyset$.
2. If $\mathbb{T}^n \setminus Lt_\sigma(G) = \emptyset$, stop; otherwise let t be the set's minimal element.
3. Compute $v = (t(p_1), \dots, t(p_m))^T$ via evaluating t on the point set \mathbb{X} .
4. If $v \in Eval(\mathcal{O})$, find a representation of v and add the corresponding polynomial to G . Then go to Step 2.
5. Add t to \mathcal{O} , v to $Eval(\mathcal{O})$ and go to step 2.

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Classical Version



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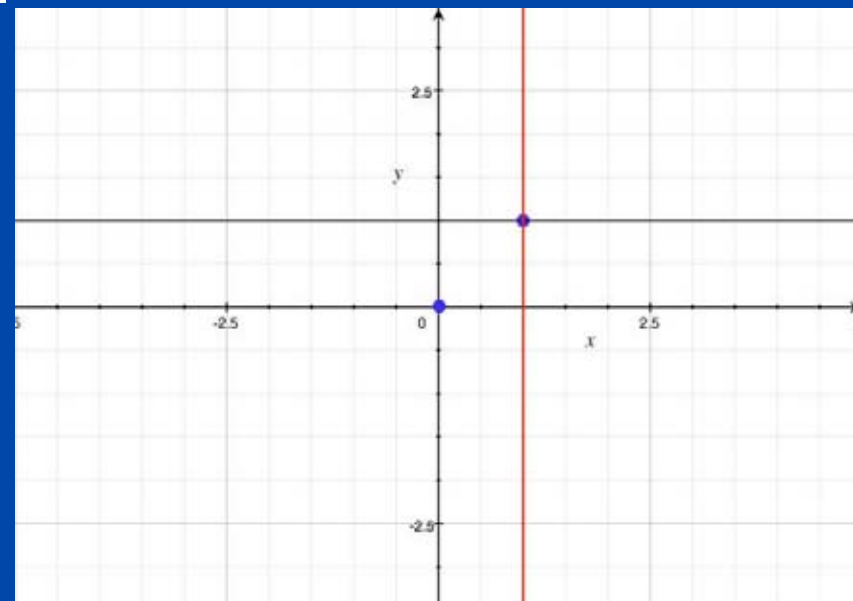
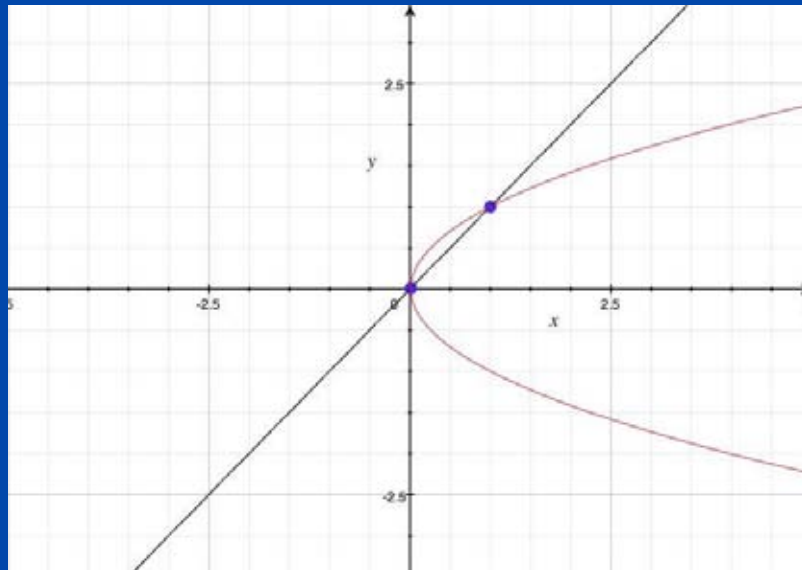
Drawbacks:

- The found relations are far away from vanishing on the points:
 - numerical error prevent accurate calculation
 - exact solution would result in an O with $\#O = \#P$ (1000 here!!)
 - The exact relations (for the perturbed data) are usually of very high degree

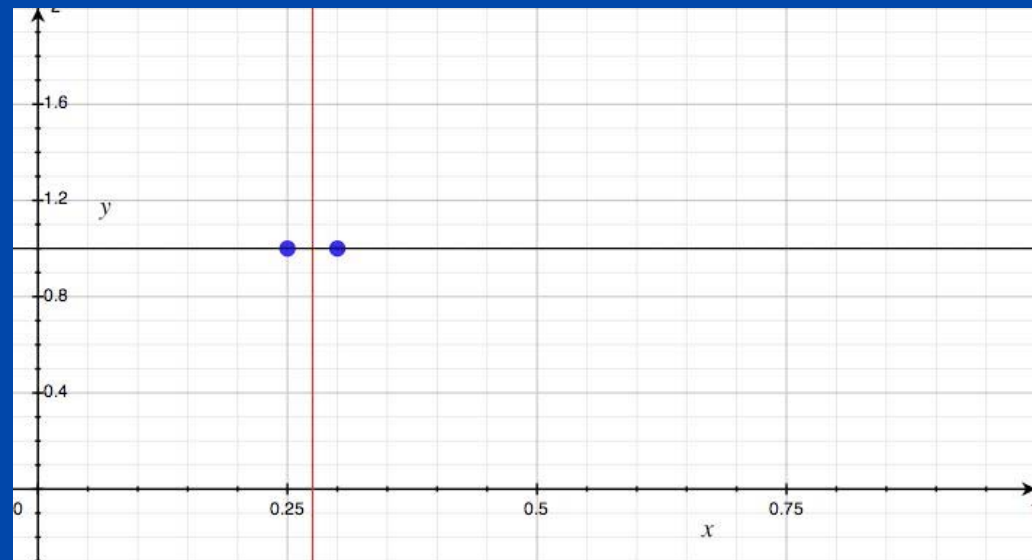
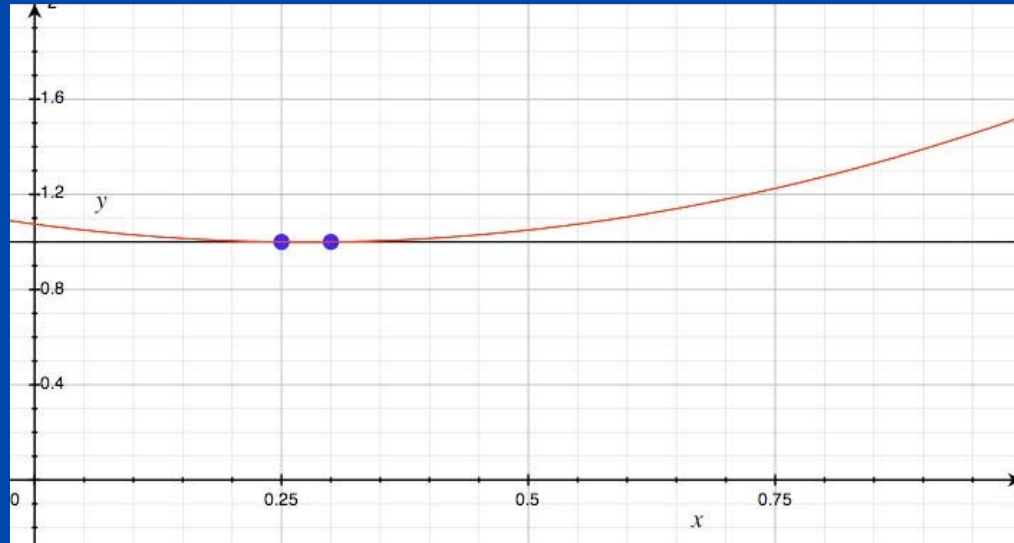
How to overcome these problems:

- Do not force the relations to pass through every point, but demand passing „close by“
- Allow points which lie “close together” to be “melt together”
- “Divide the good ones from the bad ones”
- Process blocks rather than single elements to (hopefully) prevent sub-optimal solutions and speed-up computations

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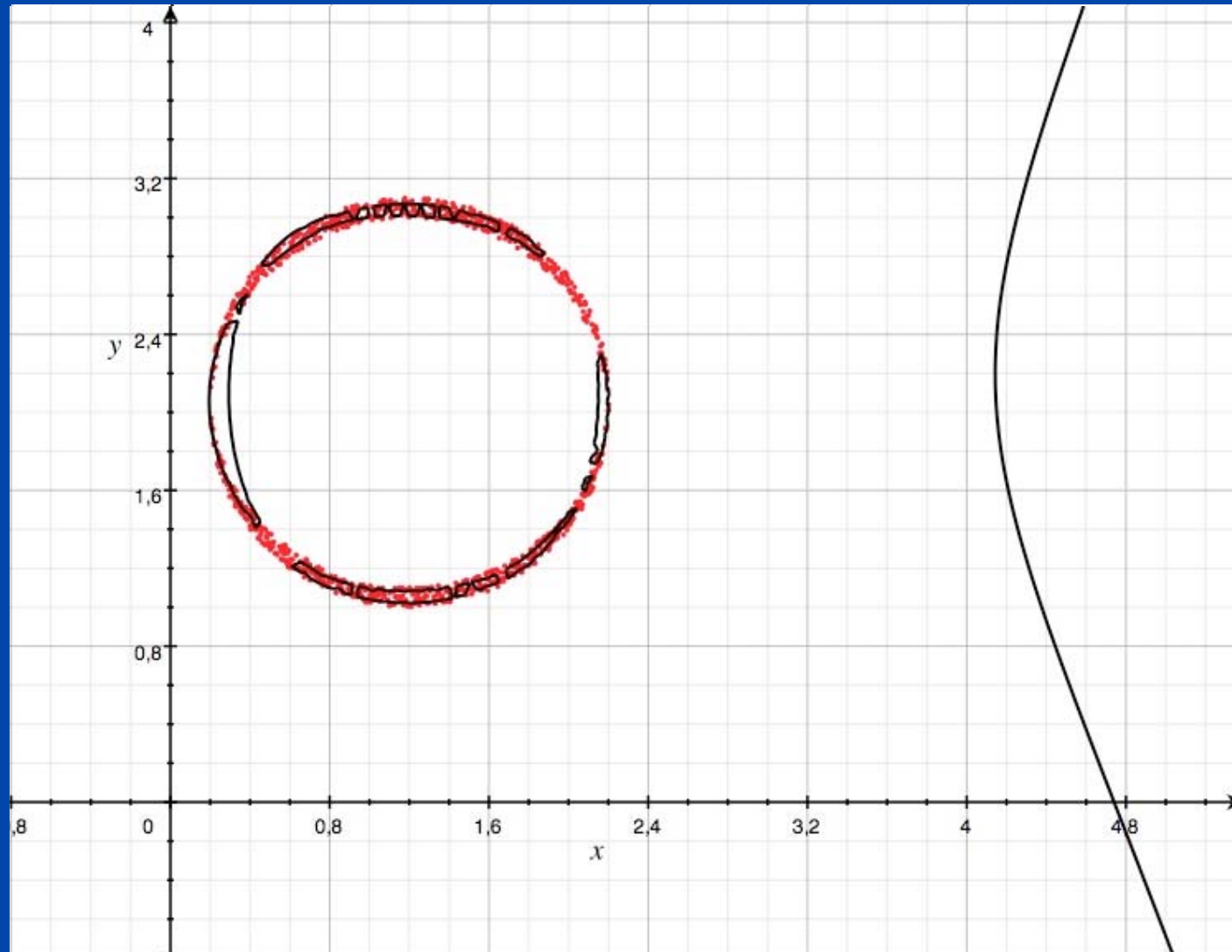


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An approximate Buchberger–Möller algorithm:

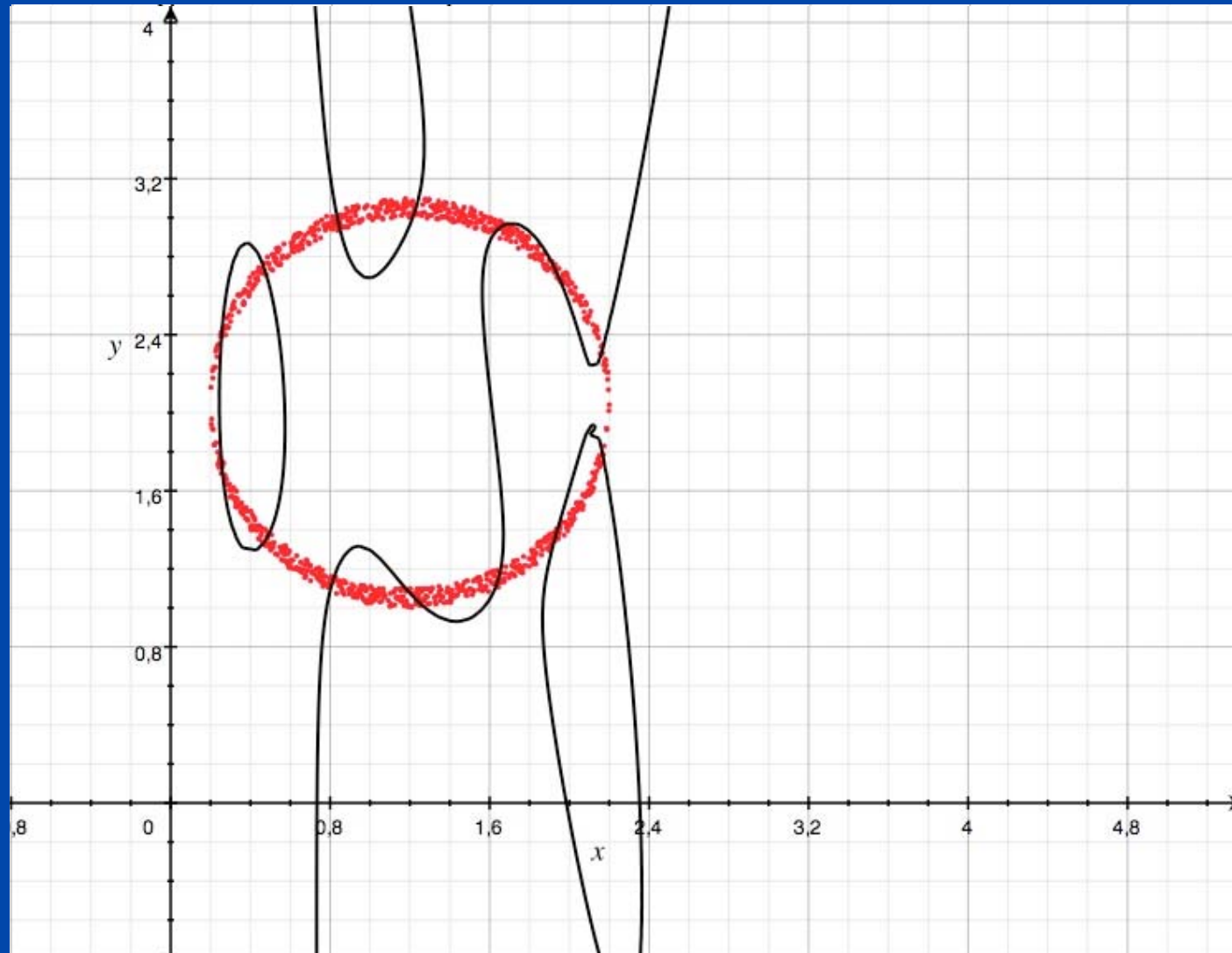
1. Set $\mathcal{O} = \emptyset$, $Eval(\mathcal{O}) = \emptyset$, $G = \emptyset$ and $d = 0$.
2. If $\mathbb{T}^n \setminus LT_\sigma(G) = \emptyset$, stop; otherwise let $T = \{t_1, \dots, t_s\}$ contain the set's polynomials of degree d .
3. Compute the matrix $V = (v(t_1), \dots, v(t_n))$, where $v(t_i) = (t_i(p_1), \dots, t_i(p_m))^T$ is t_i 's evaluation on the point set \mathbb{X} .
4. Compute the singular values of the matrix $(V \quad Eval(\mathcal{O}))$ and a basis of all singular vectors with singular values $< \varepsilon$. Represent these basis as a set of (reduced) polynomials and add them to G .
5. Add all terms in $T \setminus LT_\sigma(G)$ to \mathcal{O} and their evaluations to $Eval(\mathcal{O})$, increment d and go to step 2.

Approximate Vanishing Ideal with Singular Value Decomposition



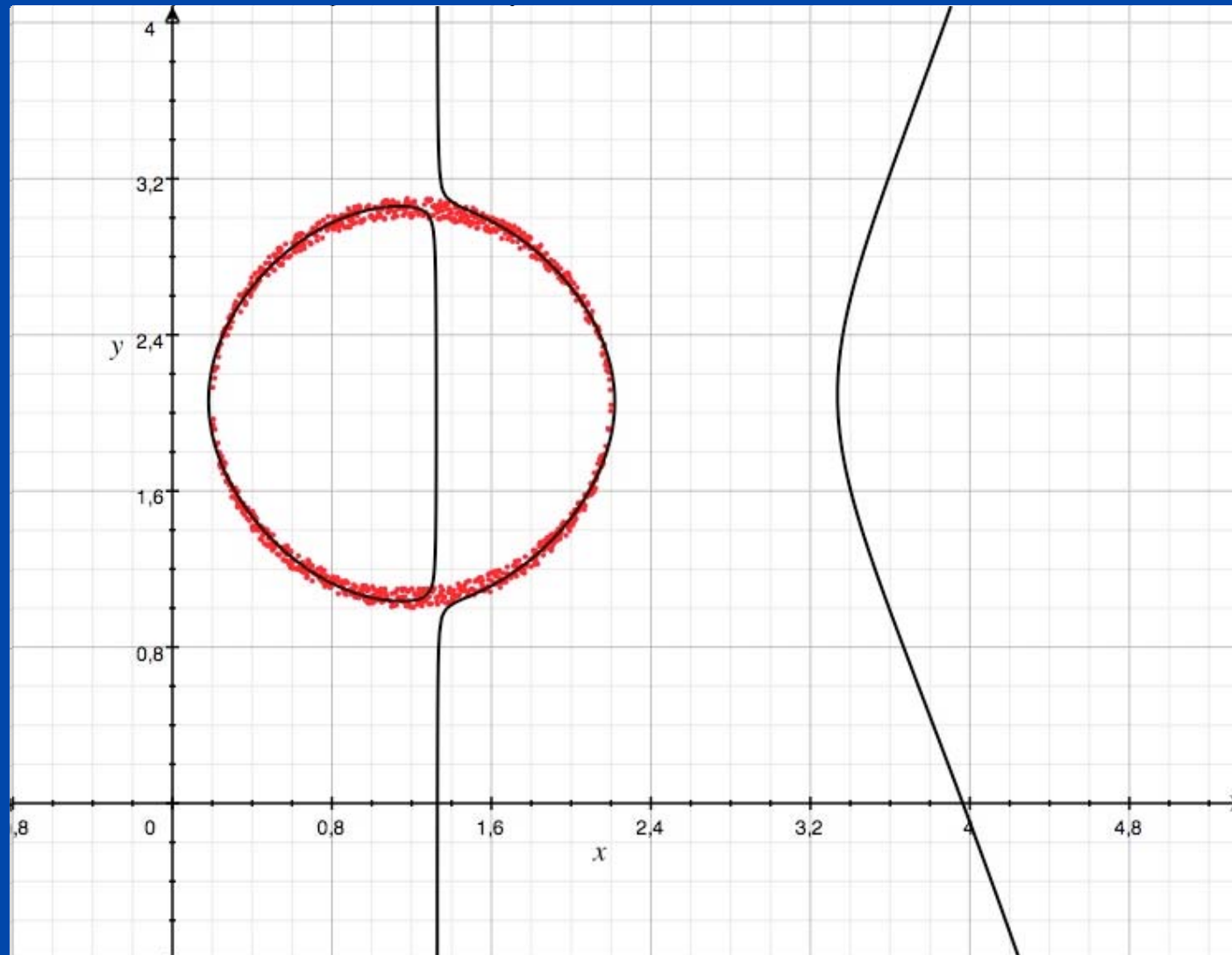
Truncate below
 $\text{eps} = 0.001$

Approximate Vanishing Ideal with Singular Value Decomposition



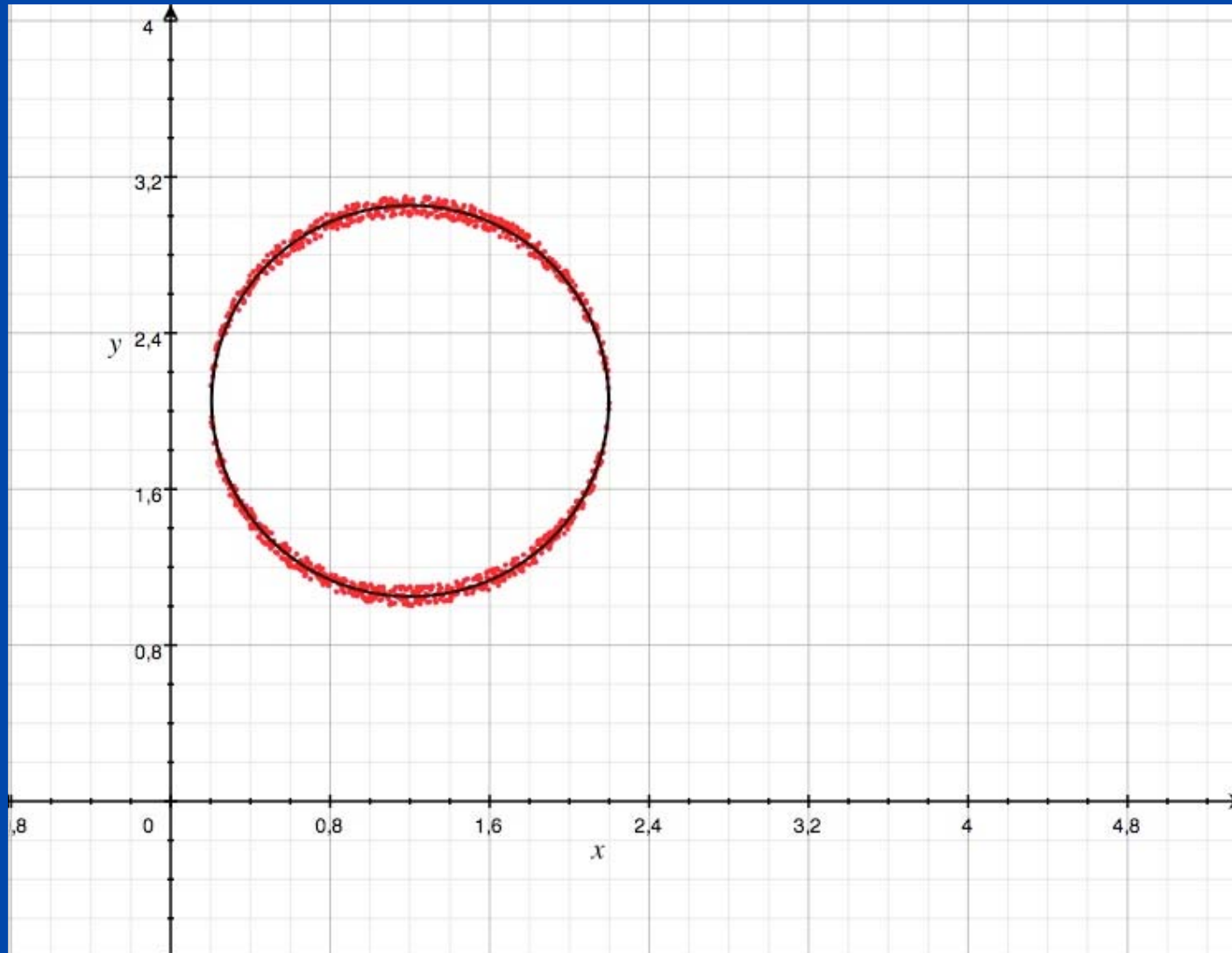
Truncate below
 $\text{eps} = 0.01$

Approximate Vanishing Ideal with Singular Value Decomposition



Truncate below
 $\text{eps} = 0.1$

Approximate Vanishing Ideal with Singular Value Decomposition

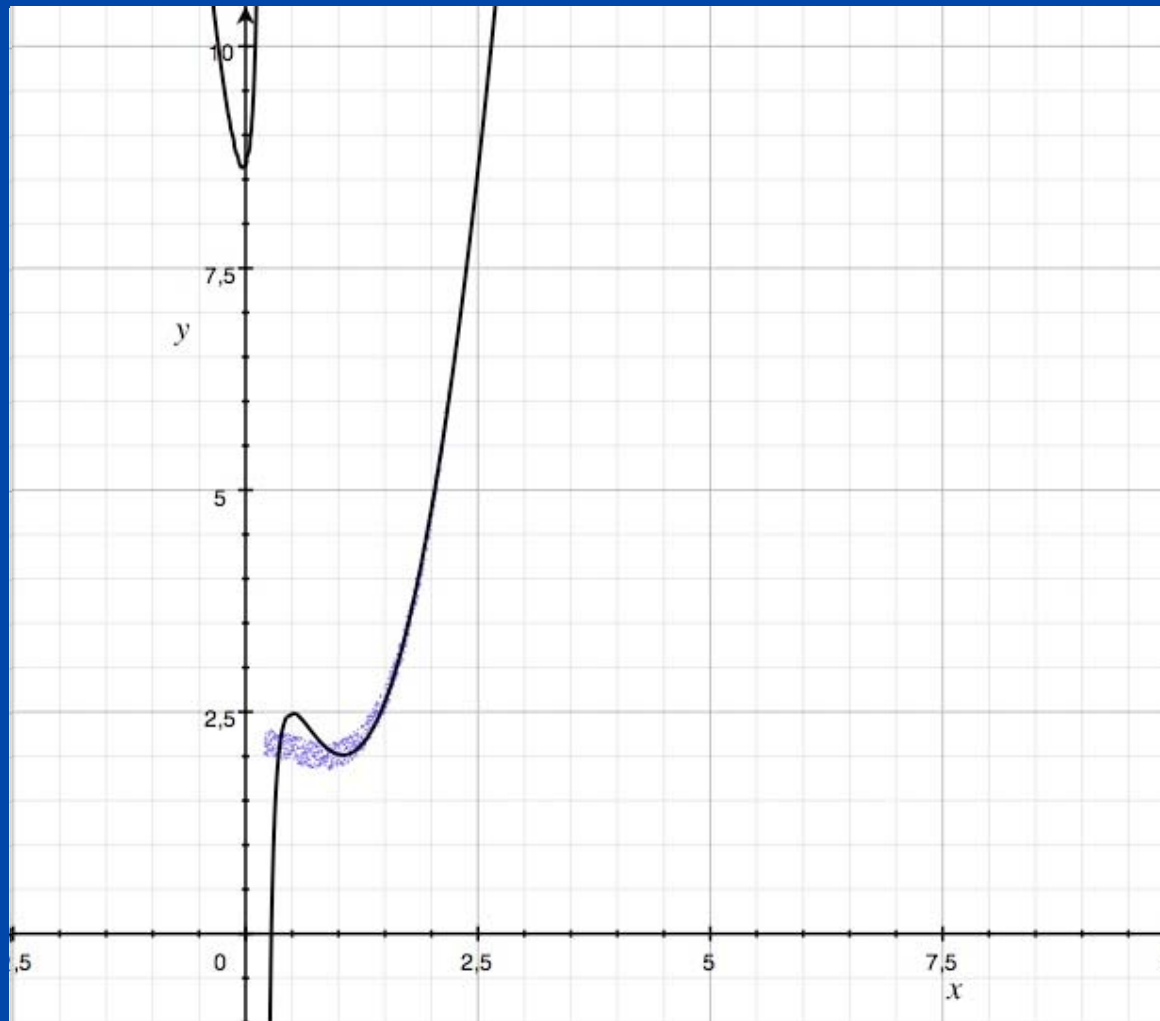


Truncate below
 $\text{eps} = 0.5$

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Another (short) example...

Approximate Vanishing Ideal with Singular Value Decomposition



Classical Version

Truncate below
 $\text{eps} = 0.7$

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An approximate Buchberger–Möller algorithm for border basis:

1. Set $\mathcal{O}_s = \emptyset$, $Eval(\mathcal{O}) = \emptyset$, $G = \emptyset$ and $d = 0$.
2. If $(\mathcal{O} \cdot \{x_1, \dots, x_n\})_d$ is empty, stop; otherwise let $T = \{t_1, \dots, t_s\}$ contain the set's polynomials of degree d .
3. Compute the matrix $V = (v(t_1), \dots, v(t_s))$, where $v(t_i) = (t_i(p_1), \dots, t_i(p_m))^T$ is t_i 's evaluation on the point set \mathbb{X} .
4. Compute the singular values of the matrix $(V Eval(\mathcal{O}))$ and a basis of all singular vectors with singular values $< \varepsilon$. Represent these basis as a set of (reduced) polynomials and add them to G .
5. Add all terms in $T \setminus LT_\sigma(G)$ to \mathcal{O} and their evaluations to $Eval(\mathcal{O})$, increment d and go to step 2.

**Timings (GB-Version)
(2024 points, 9 indets)**

	ϵ	# in basis	max deg	max m-error	mean m-error	calc. time
1	1	15	3	0.015	0.0025	0.77 s
2	0.5	19	3	0.0063	$8.1262 \cdot 10^{-4}$	0.84 s
3	0.1	24	3	$6.9260 \cdot 10^{-4}$	$2.7851 \cdot 10^{-4}$	0.82 s
4	0.01	39	4	$9.0761 \cdot 10^{-5}$	$1.7142 \cdot 10^{-5}$	1.43 s
5	0.001	59	4	$1.5547 \cdot 10^{-6}$	$1.0135 \cdot 10^{-6}$	2.34 s
6	0.0001	82	4	$4.8458 \cdot 10^{-7}$	$1.0858 \cdot 10^{-7}$	4.04 s
7	0.00001	125	4	$8.4620 \cdot 10^{-8}$	$8.0948 \cdot 10^{-9}$	7.31 s
8	0.0 (full)	260	5	$4.6954 \cdot 10^{-11}$	$2.0193 \cdot 10^{-11}$	22.04 s

TABLE 1. Results (real-world data set) for calculating a DegLex Gröbner basis

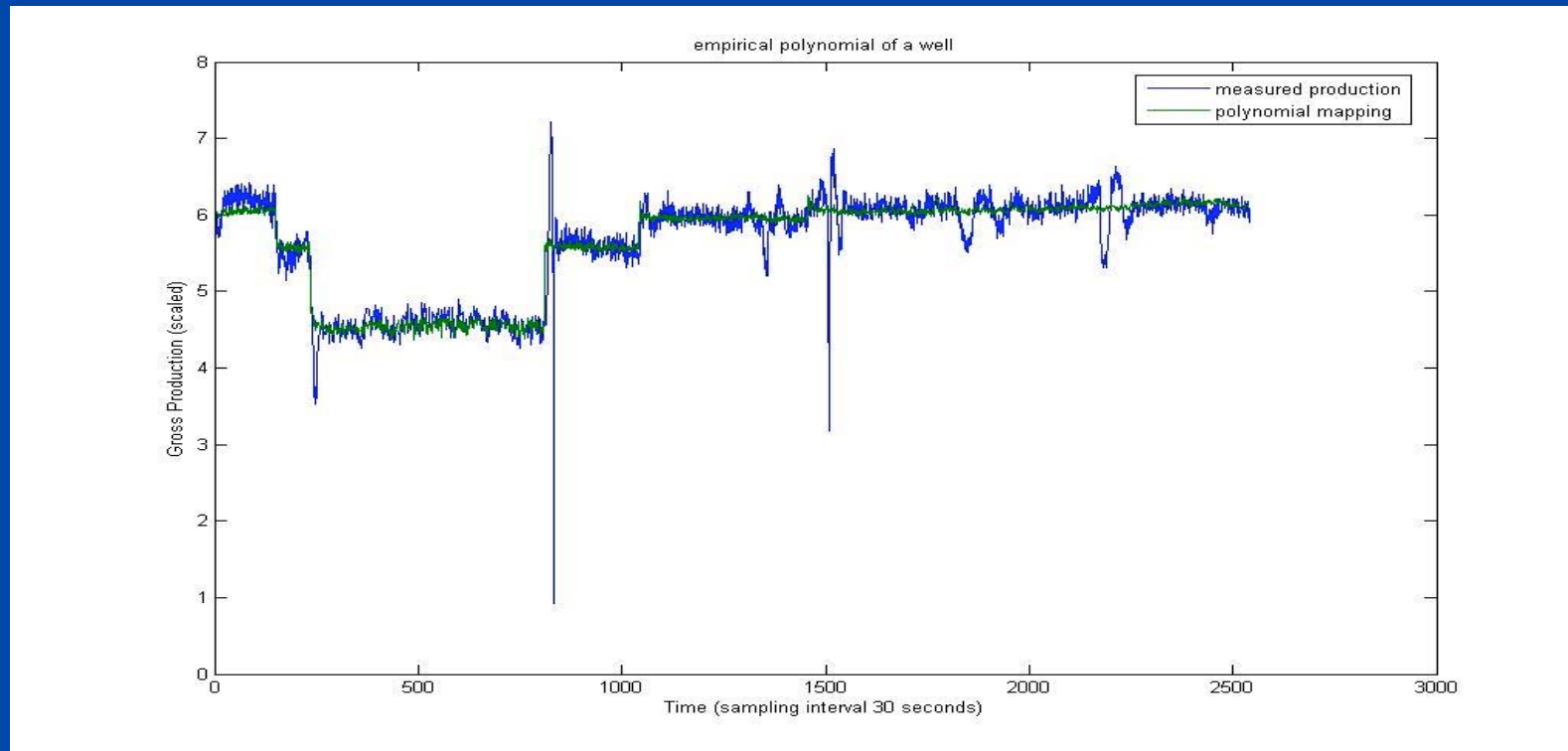
**Timings (BB-Version)
(2024 points, 9 indets)**

	ϵ	# in basis	max deg	max m-error	mean m-error	calc. time
1	1	94	6	0.0115	$5.5523 \cdot 10^{-4}$	1.86 s
2	0.5	88	5	0.0063	$3.4916 \cdot 10^{-4}$	1.72 s
3	0.1	185	8	$6.9626 \cdot 10^{-4}$	$3.1908 \cdot 10^{-5}$	4.19 s
4	0.01	163	5	$9.0761 \cdot 10^{-5}$	$3.3018 \cdot 10^{-6}$	4.60 s
5	0.001	223	5	$1.5547 \cdot 10^{-6}$	$2.1958 \cdot 10^{-7}$	8.07 s
6	0.0001	306	6	$4.8458 \cdot 10^{-7}$	$2.4311 \cdot 10^{-8}$	13.55 s
7	0.00001	345	5	$8.4620 \cdot 10^{-8}$	$3.4753 \cdot 10^{-9}$	20.52 s
8	0.0 (full)	539	5	$3.6442 \cdot 10^{-11}$	$1.3308 \cdot 10^{-11}$	53.37 s

TABLE 2. Results (real-world data set) for calculating a border basis

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Application within Shell



Calculate relations for the productions...

Typical datasize: 2000-5000 points in up to 15 indets

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Application within steel industries



Application fields:

- predict production quality
- automated quality assurance

Typical datasize: 10000-15000 points in 10-15 indets

- *solution time < 238.73 s*
- *#G = 464, #O = 391*

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Acknowledgement:

C. Fassino and J. Abbott worked in parallel on an algorithm which also computes almost vanishing ideals, but with a different approach... See:

C. Fassino. An Approximation to the Gröbner Basis of Ideals of Perturbed Point. Preprint (2006)

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Thank you! !